

A Model Specification Test for Nonlinear Stochastic Diffusions with Delay

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Abstract

The paper investigates model specification problems for nonlinear stochastic differential equations with delay (SDDE). Compared to the model specification for conventional stochastic diffusions without delay, the observed sequence does not admit a Markovian structure so that the classical testing procedures fail. To overcome this difficulty, we propose a moment estimator from the ergodicity of SDDEs and its asymptotic properties are established. Based on the proposed moment estimator, a testing procedure is derived for our model specification testing problems. Particularly, the limiting distributions of the proposed test statistic are derived under null hypotheses and the test power is obtained under some specific alternative hypotheses. Finally, a Monte Carlo simulation is conducted to illustrate the finite sample performance of the proposed test.

Keywords: Model specification test, Stochastic differential equation with delay, Moment estimator, Ergodicity, Invariant measure, Non-Markovian property.

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1 Introduction

Consider a d -dimensional stochastic differential equation with delay

$$dX(t) = b_0(X_t)dt + \sigma_0(X_t)dW(t), \quad (1)$$

where $X(t)$ denotes the state of the system at time t and $X_t = \{X(t+s) : -\tau \leq s \leq 0\}$ is called the segment process which includes the all information of $X(\cdot)$ on $[t-\tau, t]$. The $\tau > 0$ is a fixed constant representing the delay structure. The two coefficient functions $b_0(\cdot)$ and $\sigma_0(\cdot)$ are appropriate mappings of the segment process and $W(t)$ is a r -dimensional standard Brownian motion. We are interested in testing the joint parametric family $\mathcal{P} = \{(b(\cdot; \theta), \sigma(\cdot; \theta)) : \theta \in \Theta\}$, where Θ is a compact subset of \mathbb{R}^m . The parametric family \mathcal{P} provides explanatory power of understanding the underlying dynamics. This is to say that our aim is to test if the following null hypothesis holds or not

$$H_0 : b_0(\cdot) = b(\cdot; \theta), \quad \sigma_0(\cdot) = \sigma(\cdot; \theta) \text{ for some } \theta \in \Theta.$$

Throughout the paper, we always write the true parameter $\theta = \theta^* \in \Theta$ if H_0 is true even though the value of θ^* may not be given. This test is about to see if a parametric (linear) model is appropriate for a real application.

When $b_0(X_t) = b_0(X(t))$ and $\sigma_0(X_t) = \sigma_0(X(t))$ for some appropriate functions $b_0(\cdot)$ and $\sigma_0(\cdot)$ on \mathbb{R}^d , the SDDE model in (1) reduces to a classical stochastic differential equation (SDE) without delay. The model specification testing problem for such special case has been a very important topic in the previous literature since the pioneer work by Aït-Sahalia (1996). For example, there are some extensions to the method in Aït-Sahalia (1996), by Hong and Li (2005), Chen, Gao and Tang (2008), and Aït-Sahalia, Fan and Peng (2009), especially, see Hong and Li (2005) for the kernel estimation for transition density, Chen, Gao and Tang (2008) for transitional density using the empirical likelihood, and Aït-Sahalia, Fan and Peng (2009) for a specification test for the transition density of a discretely sampled continuous-time jump-diffusion process.

Different from the aforementioned papers, we will assume that the joint parametric family \mathcal{P} admits a delay dependence structure in our paper. The motivation of delay dependence stems from the fact that many of the phenomena witnessed in applications do not have an immediate effect from the moment of their occurrence. With such an important feature, SDDEs are widely used in stochastic modeling in practice. For example, applied works focusing on SDDEs in the literature, include, to name just a few, the work by Mao (2007), Bratsun, Volfson, Tsimring and Hasty (2005), Hobson and Rogers (1998), Steiner, Stewart and Matějka (2017), Marschak (1971), Lawrence (2012), Lei and Mackey (2007), Rihan (2021), Stoica (2005), Karatzas (1996), Hale and Lunel (2013), Chen and Yu (2014), Ivanov and Swishchuk (2008), Arriojas, Hu, Mohammed and Pap (2007), and references therein, with particular applications in the analysis of stability in automatic control in stochastic systems, gene regulation, inertia and delay in decision-making, stochastic volatility, stochastic games, economics of information systems, optimal control in economics, and a delayed Black-Schole formulation and option pricing in finance.

The parameter estimation and statistical inference for SDDEs also receive lots of attention in the literature, see, for example, Benke and Pap (2017), Gushchin and Kückler (1999), Kückler and Kutoyants (2000), Kückler and Sørensen (2010, 2013), Reiss (2005), and references therein. In the

literature, it is commonly assumed that the drift coefficient is linear and the diffusion coefficient is a constant, and the observations are in real-time in aforementioned papers. For a different small perturbation approach, the reader is referred to the paper by Kutoyants (2021) and references therein. To the best of our knowledge, there is no work yet concerning with the model specification problem for general nonlinear SDDEs especially with discrete-time observations. The paper aims to fill this gap by providing an efficient testing procedure for those general cases.

More specifically, we will construct a testing procedure using the ergodicity of non-linear SDDEs for the model specification problem. Such a generalization allows us to work on more complex model specification problems with delay in practice. Due to the non-Markovian structure, the classical testing method using transition probability for Markovian observations as in Aït-Sahalia (1996), Hong and Li (2005), Chen, Gao and Tang (2008), and Aït-Sahalia, Fan and Peng (2009), is not directly applicable here. To propose a testing procedure, our approach consists of two steps. First, we will introduce a moment estimator and provide its asymptotic properties. Our estimator is inspired by the ergodicity of SDDEs similar to Küchler and Sørensen (2013) and different from the small perturbation approach in Kutoyants (2021). Then, based on the proposed moment estimator, we construct a statistic and establish its limiting distributions, which can be used in our model specification problem for SDDEs. Because the diffusion coefficient can be estimated non-parametrically using in-fill asymptotics, our methods are designed particularly for testing the drift coefficients. Therefore, we will assume $\sigma_0(\cdot)$ being independent of θ in the future.

The well-posed results (such as the existence and uniqueness) for the SDDE in (1) can be found in Mao (2007). Define an operator on \mathcal{A} for any twice continuously differentiable function $f(\cdot) : \mathbb{R}^d \mapsto \mathbb{R}$ by

$$\mathcal{A}f(\eta; \theta) = \langle b(\eta; \theta), \nabla f(\eta(0)) \rangle + \frac{1}{2} \text{trace} \left[\sigma(\eta) \sigma^\top(\eta) D^2 f(\eta(0)) \right],$$

where η denotes a possible path of the segment process (see (3) below), ∇f is the gradient of f , and $D^2 f$ is the Hessian matrix of f . We also write $\mathcal{A}_0 f(\eta) = \mathcal{A}f(\eta; \theta^*)$ for the true $\theta = \theta^*$. It follows from Hale and Lunel (2013) that for a regular function $f(\cdot)$, the following process

$$f(X(t)) - f(X(0)) - \int_0^t \mathcal{A}_0 f(X_s) ds$$

is a local martingale. Actually, \mathcal{A} can be seen as the infinitesimal generator for the segment process $\{X_t\}$. To work on the testing problem in our paper, we need to assume the solution process to be exponential ergodic with a unique invariant measure μ . In such case, the observation is asymptotically stable which coincides with the classical stable assumptions for observations in the previous literature. The results concerning with the exponential ergodicity can be found in Appendix.

The rest of the paper is arranged as follows. We present the definition of moment estimator and prove its limit theorems in Section 2. Then, a testing procedure for testing our model specification problem is developed in Section 2 too. Some simulation results to justify our theory are illustrated in Section 3. We summarize our conclusions in Section 4. The mathematical proofs of the main results are relegated to Section 5. Finally in Appendix, some limit theorems for SDDEs are recalled, especially on the exponential ergodicity theory.

2 A Specification Test

2.1 Moment Estimator

In this section, our aim is on presenting the definition of our estimator which is called a moment estimator since the definition depends on H_0 and takes a moment estimator form.

Suppose we observe the SDDE in (1) with a time-window Δ and obtain a sequence of observations $\{Z_i\}_{i=0}^n$, where $Z_i = X(i\Delta)$, and that there also exists a set of regular functions $\mathbf{f} = \{f_k : k = 1, \dots, m\}$. To emphasize the dependence of θ , we write by $\mu(\cdot; \theta)$ the unique invariant measure of X_t (see Appendix). It is well-known that for $k = 1, \dots, m$,

$$\int_{\mathcal{C}} \mathcal{A}f_k(\eta; \theta^*) \mu(d\eta; \theta^*) = 0.$$

As X is exponential ergodic, by the law of large numbers (LLN); see, for instance, Mao (2007), we have

$$\frac{1}{T} \int_{\tau}^T \mathcal{A}f_k(X_t; \theta^*) dt \rightarrow \int_{\mathcal{C}} \mathcal{A}f_k(\eta; \theta^*) \mu(d\eta; \theta^*) = 0$$

almost surely as $T \rightarrow \infty$, where \mathcal{C} is defined in (3) later. Replacing the continuous-time process X above by the sequence of discrete time observations $\{Z_i\}_{i=0}^n$, we define

$$\begin{aligned} & \widehat{A}_{n,\Delta}(f_k; \theta) \\ &= \frac{1}{n} \sum_{i=m_\Delta}^n \left[\tilde{b}_\Delta^\top(Z_{i-m_\Delta}, \dots, Z_i; \theta) \nabla f_k(Z_i) + \frac{1}{2} \text{trace} \left([\tilde{\sigma}_\Delta^\top \tilde{\sigma}_\Delta](Z_{i-m_\Delta}, \dots, Z_i) D^2 f_k(Z_i) \right) \right], \end{aligned}$$

where $m_\Delta = \lfloor \tau/\Delta \rfloor$, the largest integer smaller than or equal to τ/Δ , and $\tilde{b}_\Delta(\cdot)$ and $\tilde{\sigma}_\Delta(\cdot)$ are some appropriately approximations chosen for $b(\cdot)$ and $\sigma(\cdot)$ in (1). Here, note that different from $b(\cdot)$ and $\sigma(\cdot)$, $\tilde{b}_\Delta(\cdot)$ and $\tilde{\sigma}_\Delta(\cdot)$ are finitely dimensional functions. For such case, the $\widehat{A}_{n,\Delta}(f_k; \theta)$ is essentially an approximation of

$$A_{n\Delta}(f_k; \theta) = \frac{1}{n\Delta} \int_{\tau}^{n\Delta} \left[b^\top(X_t; \theta) \nabla f_k(X(t)) + \frac{1}{2} \text{trace} \left([\sigma^\top \sigma](X_t) D^2 f_k(X(t)) \right) \right] dt.$$

A natural idea of defining the moment estimator is to solve the following equations for θ ,

$$\widehat{A}_{n,\Delta}(f_k; \theta) = 0, \quad k = 1, \dots, m.$$

Because the solution may not exist, in our paper, we define the moment estimator $\widehat{\theta}_{n,\Delta}(\mathbf{f})$ as an m -dimensional vector in the compact set Θ by

$$\widehat{\theta}_{n,\Delta}(\mathbf{f}) = \underset{\theta \in \Theta}{\operatorname{argmin}} \sum_{k=1}^m \left| \widehat{A}_{n,\Delta}(f_k; \theta) \right|. \quad (2)$$

As Θ is compact, $\widehat{\theta}_{n,\Delta}(\mathbf{f})$ is well-defined. Write the error term (after an appropriate scaling) by

$$\gamma_{n,\Delta} = \sqrt{n\Delta} \sum_{k=1}^m \left| \widehat{A}_{n,\Delta}(f_k; \widehat{\theta}_{n,\Delta}(\mathbf{f})) \right| = \sqrt{n\Delta} \inf_{\theta \in \Theta} \sum_{k=1}^m \left| \widehat{A}_{n,\Delta}(f_k; \theta) \right|,$$

and then, the limit behavior of the error $\gamma_{n,\Delta}$ will play an important role in the later analytic study.

It is always assumed throughout the paper that $\Delta = \Delta_n \rightarrow 0$, $n \rightarrow \infty$ and $n\Delta_n \rightarrow \infty$. The last $n\Delta_n \rightarrow \infty$ allows us to apply the LLN and the central limit theorem (CLT) for SDDEs and is also sufficient for $(n - m\Delta_n)/n \rightarrow 1$. Here, we would like to emphasize that the assumption $\Delta_n \rightarrow 0$ is to guarantee our moment estimator being unbiased in our paper. The unbiasedness of the moment estimator is critical in our testing procedure. In fact, without loss of generality, we also assume that $\sum_{n=1}^{\infty} \Delta_n < \infty$ in the following asymptotic theory. Otherwise, we take a subsequence (n_j, Δ_{n_j}) of (n, Δ_n) such that $\sum_{j=1}^{\infty} \Delta_{n_j} < \infty$. Until now, we have unveiled the definition of our moment estimator $\hat{\theta}_{n,\Delta_n}(\mathbf{f})$ given in (2). Our main goal is to study the consistency and asymptotic normality so that one can construct a test statistic for the testing problem. In the sequel, L is a tentative constant which may vary from place to place. We also write $O_p(1)$ and $o_p(1)$ by a term which is bounded and converges to 0 in probability respectively.

2.2 Asymptotic Properties

First, we establish the consistency of our moment estimator if H_0 is true. Our proof relies on the ergodicity theory for SDDEs in Appendix. To this end, define the space

$$\mathcal{C} = \left\{ \eta : [-\tau, 0] \mapsto \mathbb{R}^d \mid \eta(\cdot) \text{ is continuous on } [-\tau, 0] \right\}, \quad (3)$$

equipped with the sup-norm metric $\|\eta\|_{\mathcal{C}} = \sup_{-\tau \leq s \leq 0} |\eta(s)|$. For any $\eta \in \mathcal{C}$, we write the δ -increment functional by

$$w_{\delta}(\eta) = \sup_{\substack{-\tau \leq u \leq v \leq 0 \\ |u - v| \leq \delta}} |\eta(u) - \eta(v)|.$$

Now, we need the following assumption to investigate the large sample theory.

Assumption 1. *Suppose that $f_k \in \mathbf{f}$ is twice continuous differentiable with bounded second order derivatives satisfying:*

(i) θ^* is the unique solution

$$\int_{\mathcal{C}} \mathcal{A}f_k(\eta; \theta) \mu(d\eta; \theta^*) = 0 \text{ for all } k = 1, \dots, m.$$

Here, we recall that μ is the unique invariant measure of X_t .

(ii) The rank of the matrix $R(\theta^*) = (r_1(\theta^*), \dots, r_m(\theta^*))$ is m , where

$$r_k(\theta) = \int_{\mathcal{C}} \partial_{\theta} \mathcal{A}f_k(\eta; \theta) \mu(d\eta; \theta). \quad (4)$$

(iii) For any $\eta \in \mathcal{C}$, there exist $\tilde{b}_{\Delta} : (\mathbb{R}^d)^{m_{\Delta}+1} \times \Theta \mapsto \mathbb{R}^d$ and $\tilde{\sigma}_{\Delta} : (\mathbb{R}^d)^{m_{\Delta}+1} \times \Theta \mapsto \mathbb{R}^{d \times r}$ such that

$$\begin{aligned} & |\tilde{b}_{\Delta}(\eta(-m_{\Delta} * \Delta), \dots, \eta(0); \theta)| + |\tilde{\sigma}_{\Delta}(\eta(-m_{\Delta} * \Delta), \dots, \eta(0))| \leq L(1 + \theta)(1 + \|\eta\|_{\mathcal{C}}), \\ & |\partial_{\theta} b(\eta; \theta)| + |\partial_{\theta}^2 b(\eta; \theta)| + |\partial_{\theta} \tilde{b}_{\Delta}(\eta(-m_{\Delta} * \Delta), \dots, \eta(0); \theta)| \\ & \quad + |\partial_{\theta}^2 \tilde{b}_{\Delta}(\eta(-m_{\Delta} * \Delta), \dots, \eta(0); \theta)| \leq L(1 + \|\eta\|_{\mathcal{C}}), \\ & |b(\eta; \theta) - \tilde{b}_{\Delta}(\eta(-m_{\Delta} * \Delta), \dots, \eta(0); \theta)| + |\sigma(\eta; \theta) - \tilde{\sigma}_{\Delta}(\eta(-m_{\Delta} * \Delta), \dots, \eta(0); \theta)| \\ & \quad \leq L(1 + |\theta|)w_{\Delta}(\eta), \\ & |\partial_{\theta} b(\eta; \theta) - \partial_{\theta} \tilde{b}_{\Delta}(\eta(-m_{\Delta} * \Delta), \dots, \eta(0); \theta)| \leq Lw_{\Delta}(\eta). \end{aligned}$$

To prove the consistency, we proceed with the following proposition.

Proposition 1. *Suppose Assumptions 1 and 2 hold. It follows that*

$$\lim_{n \rightarrow \infty} \sup_{\theta \in \Theta} \left| \widehat{A}_{n, \Delta_n}(f_k; \theta) - \int_{\mathcal{E}} \mathcal{A}f_k(\eta; \theta) \mu(d\eta; \theta^*) \right| = 0$$

almost surely, where Assumption 2 is provided in Section 5.

Now, let us present the consistency of the estimator under H_0 with its proof given in Section 5.

Theorem 1 (Consistency). *Suppose Assumptions 1 and 2 hold. Under H_0 , it follows that*

$$\widehat{\theta}_{n, \Delta_n} \rightarrow \theta^* \tag{5}$$

almost surely as $n \rightarrow \infty$. Consequently, the moment estimator is consistent.

Next, we will prove the asymptotic normality for the moment estimator $\widehat{\theta}_{n, \Delta_n}(\mathbf{f})$ defined in (2). We proceed with the following estimate for the error term γ_{n, Δ_n} with its proof given in Section 5.

Lemma 1. *Under Assumptions 1 and 2, if Θ has neighborhood of θ^* , then $\gamma_{n, \Delta_n} = 0$ when n is large.*

From the estimate for γ_{n, Δ_n} in Lemma 1, we will divide our testing problem into two different cases (I): Θ has a neighborhood of θ^* ; (II): $\Theta = \{\theta^*\}$. We want to mention that we do not have $\gamma_{n, \Delta_n} \rightarrow 0$ in probability for Case II. It is obvious that Case II is trivial in the estimator step so that our focus is only on Case I. The following is our result on the asymptotic normality of $\widehat{\theta}_{n, \Delta_n}(\mathbf{f})$ with its proof given in Section 5.

Theorem 2 (Asymptotic Normality). *Suppose Assumptions 1 and 2 hold and Θ has a neighborhood of θ^* . As $n \rightarrow \infty$ with $\sqrt{n}\Delta_n \rightarrow 0$, then under H_0 , it follows that*

$$\sqrt{n\Delta_n} [\widehat{\theta}_{n, \Delta_n}(\mathbf{f}) - \theta^*] \rightarrow N(0, \Sigma(\mathbf{f}; \theta^*)) \tag{6}$$

in distribution, where $\Sigma(\mathbf{f}; \theta^)$ is defined as*

$$r_k^\top(\theta^*) \Sigma(\mathbf{f}; \theta^*) r_k(\theta^*) = \int_{\mathcal{E}} |\sigma^\top(\eta) \nabla f_k(\eta(0))|^2 \mu(d\eta; \theta^*) \text{ for all } k = 1, \dots, m, \tag{7}$$

with $r_k(\theta)$ defined in (4).

Note that the true θ^* is not obtainable, we provide the following asymptotic normality with variance being independent of θ^* . Together with Lemma 2 in Appendix, we have the following proposition.

Proposition 2. *Suppose assumptions in Lemma 2 in Appendix and Assumption 1 hold. As $n \rightarrow \infty$ with $\sqrt{n}\Delta_n \rightarrow 0$, under H_0 , it follows that*

$$\sqrt{n\Delta_n} \cdot \Sigma^{-1/2}(\mathbf{f}; \widehat{\theta}_{n, \Delta_n}(\mathbf{f})) \left[\widehat{\theta}_{n, \Delta_n}(\mathbf{f}) - \theta^* \right] \rightarrow N(0, 1)$$

in distribution.

Until now, we have obtained the asymptotic normality for our moment estimator $\widehat{\theta}_{n, \Delta}(\mathbf{f})$. While we can not directly apply such asymptotic normality to our hypothesis testing problem as the true θ^* is not obtainable. Therefore, we will continue to construct a statistic for our model testing problem in Section 2.3.

2.3 Test Statistic

In this section, we will propose a statistic and present the corresponding testing procedure for our model testing problem. Let $f_0 : \mathbb{R}^d \mapsto \mathbb{R}$ and define the statistic as follows:

$$\widehat{A}_{n,\Delta}(f_0; \widehat{\theta}_{n,\Delta}(\mathbf{f})) = \sqrt{\frac{\Delta}{n}} \sum_{i=m_\Delta}^n \left[\widehat{b}_\Delta^\top(Z_{i-m_\Delta}, \dots, Z_i; \widehat{\theta}_{n,\Delta}(\mathbf{f})) \nabla f_0(Z_i) + \frac{1}{2} \text{trac} \left([\widehat{\sigma}_\Delta^\top \widehat{\sigma}_\Delta](Z_{i-m_\Delta}, \dots, Z_i) D^2 f_0(Z_i) \right) \right]$$

Now, we are ready to present the our main results of the paper. The first theorem concerns with the asymptotic normality for Case I in Theorem 3 and the second theorem is for Case II in Theorem 4 with their proofs given in Section 5.

Theorem 3. *Let all assumptions in Proposition 2 hold. Suppose that f_0 is twice continuous differentiable with bounded second order derivatives. Under H_0 , if $\sigma(f_0, \mathbf{f}; \theta^*) \neq 0$, as $n \rightarrow \infty$ with $\sqrt{n}\Delta_n \rightarrow 0$, we have*

$$\widehat{T}_{n,\Delta_n}(f_0, \mathbf{f}; \widehat{\theta}_{n,\Delta_n}(\mathbf{f})) = \sigma^{-1}(f_0, \mathbf{f}; \widehat{\theta}_{n,\Delta_n}(\mathbf{f})) \cdot \widehat{A}_{n,\Delta_n}(f_0; \widehat{\theta}_{n,\Delta_n}(\mathbf{f})) \rightarrow N(0, 1) \quad (8)$$

in distribution, where

$$r_0(\theta) = \int_{\mathcal{C}} \partial_\theta \mathcal{A}f_0(\eta; \theta) \mu(d\eta; \theta),$$

$$\sigma^2(f_0, \mathbf{f}; \theta) = \int_{\mathcal{C}} \left[\left[R^{-1}(\theta) r_0(\theta) \right]^\top \begin{pmatrix} \sigma^\top(\eta) \nabla f_1(\eta(0)) \\ \vdots \\ \sigma^\top(\eta) \nabla f_m(\eta(0)) \end{pmatrix} - \sigma^\top(\eta) \nabla f_0(\eta(0)) \right]^2 \mu(d\eta; \theta).$$

Here f_0 can not be a linear combination of \mathbf{f} because $\sigma^2(f_0, \mathbf{f}; \theta) = 0$ in such a case. This coincides with our intuition from the definition of our moment estimator as an infimum point using \mathbf{f} . We need more information of the observations through applying a new f_0 to construct the test statistic to fulfill asymptotic normality.

Theorem 4. *Let $H_0 : \theta = \theta_0$ and $H_1 : \theta = \theta_1$ with $\theta_0 \neq \theta_1$. Under H_0 , as $n \rightarrow \infty$ with $\sqrt{n}\Delta_n \rightarrow 0$ if $v^{-1}(\mathcal{A}f_0(\cdot; \theta_0); \theta_0) \neq 0$, we have*

$$v^{-1}(\mathcal{A}f_0(\cdot; \theta_0); \theta_0) \cdot \widehat{A}_{n,\Delta_n}(f_0; \theta_0) \rightarrow N(0, 1) \quad (9)$$

in distribution. Moreover, under H_1 , if f_0 satisfies $\int_{\mathcal{C}} \mathcal{A}f_0(\eta; \theta_0) \mu(d\eta; \theta_1) \neq 0$, then

$$v^{-1}(\mathcal{A}f_0(\cdot; \theta_0); \theta_0) \cdot \widehat{A}_{n,\Delta_n}(f_0; \theta_0) \rightarrow \infty$$

in probability so that the test power converges to 1 with a rate of $(n\Delta_n)^{-1}$.

Remark 1. (1) Even though the closed forms of $\sigma(f_0, \mathbf{f}; \theta)$ and $v(\mathcal{A}f(\cdot; \theta); \theta)$ as functions of θ may not be obtainable, their values can be computed numerically through an independent Monte-Carlo method without using the observations. Therefore, we can treat $\sigma(f_0, \mathbf{f}; \theta)$ and $v(\mathcal{A}f(\cdot; \theta); \theta)$ as known functions in testing procedure.

(2) When selecting f_0 , it is important that $\int_{\mathcal{C}} \mathcal{A}f_0(\eta; \theta^*) \mu(d\eta; \theta_1) \neq 0$ for a good test power. We will present a concrete example to illustrate this in simulation study later.

With the above limiting results, our testing procedure can be summarized as follows:

Case I (i.e. Θ has a neighborhood of θ^*): reject H_0 if $|\sigma^{-1}(f_0, \mathbf{f}; \widehat{\theta}_{n, \Delta_n}(\mathbf{f})) \cdot \widehat{A}_{n, \Delta_n}(f_0, \widehat{\theta}_{n, \Delta_n}(\mathbf{f}))| \geq z_{\alpha/2}$, where $z_{\alpha/2}$ is the 100(1 - $\alpha/2$) percentile of a standard normal distribution.

Case II (i.e. $H_0 : \theta = \theta^*$): reject H_0 if $|v^{-1}(\mathcal{A}f_0(\cdot; \theta^*); \theta^*) \cdot \widehat{A}_{n, \Delta_n}(f_0, \theta^*)| \geq z_{\alpha/2}$.

Our theory established above concludes that the probabilities of falsely rejecting H_0 for both Case I and Case II are asymptotically α as $n \rightarrow \infty$, $\Delta_n \rightarrow 0$, $n\Delta_n \rightarrow \infty$ and $\sqrt{n}\Delta_n \rightarrow 0$.

3 Simulation Study

We consider testing a generalized Vasicek model as in Vasicek (1977) with delay,

$$dX(t) = [a_0 - b_0X(t) + \theta b_1(X(t - \tau))]dt + \sigma dW(t)$$

for some $\theta \in \Theta = [-l, l]$. As we mainly focus on the delay structure in our paper, we will set a_0 , b_0 , and σ as given constants in our simulation example. The b_1 will be a non-linear function which distinguishes our results from the previous result in Kuchler and Sørensen (2013) and so on.

As the parameter θ is one dimensional in our example, we only pick a function $f : \mathbb{R} \mapsto \mathbb{R}$ such that $\int_{\mathcal{E}} f'(\eta(0))\eta(-1)\mu(d\eta; \theta^*) \neq 0$. Our moment estimator is defined by

$$\widehat{\theta}_{n, \Delta} = \Pi \left[\frac{\sum_{i=m_{\Delta}}^n [(b_0Z_i - a_0)f'(Z_i) - \sigma^2 f''(Z_i)/2]}{\sum_{i=m_{\Delta}}^n [b_1(Z_{i-m_{\Delta}})f'(Z_i)]} \right],$$

where Π is the projection from \mathbb{R} to $[-l, l]$. By (20), a simple calculation yields that

$$r(\theta) = \int_{\mathcal{E}} f'(\eta(0))b_1(\eta(-\tau))\mu(d\eta; \theta) (\neq 0) \text{ and } r_0(\theta) = \int_{\mathcal{E}} f'_0(\eta(0))b_1(\eta(-\tau))\mu(d\eta; \theta)$$

It is not difficult to see that

$$\sigma^2(f_0, \mathbf{f}; \theta) = \sigma^2 \int_{\mathcal{E}} \left[f'_0(\eta(0)) - \frac{r_0(\theta)}{r(\theta)} f'(\eta(0)) \right]^2 \mu(d\eta; \theta).$$

Now, let us present a concrete example to illustrate our results. Set $a_0 = 0$, $b_0 = 5$, $\sigma = 1$, $\tau = 0.1$, $b_1(x) = I(|x| < 1)$, and $f(x) = x$, $f_0(x) = x^2/2$. For this case the moment estimator and testing statistic are

$$\begin{aligned} \widehat{\theta}_{n, \Delta}(\mathbf{f}) &= \Pi \left[\frac{\sum_{i=m_{\Delta}}^n [b_0Z_i - a_0]}{\sum_{i=m_{\Delta}}^n b_1(Z_{i-m_{\Delta}})} \right] \\ \widehat{T}_{n, \Delta}(f_0, \mathbf{f}; \widehat{\theta}_{n, \Delta}(\mathbf{f})) &= \sigma^{-1}(f_0, \mathbf{f}; \widehat{\theta}_{n, \Delta}(\mathbf{f})) \sqrt{\frac{\Delta}{n}} \sum_{i=m_{\Delta}}^n \left(Z_i[a_0 - b_0Z_i + \widehat{\theta}_{n, \Delta}(\mathbf{f})b_1(Z_{i-m_{\Delta}})] + 1/2 \right), \\ \sigma^2(f_0, \mathbf{f}; \theta) &= \sigma^2 \int_{\mathcal{E}} \left[\eta(0) - \frac{r_0(\theta)}{r(\theta)} \right]^2 \mu(d\eta; \theta) \end{aligned}$$

where Π is the projection from \mathbb{R} to Θ . Here, we note that $\sigma^2(f_0, \mathbf{f}; \cdot)$ can be calculated by an independent Monte-Carlo simulation without using the observations. When simulating the observations, we use step size $\delta = \Delta/10$ and work out $n_{\delta} = 10 * n$ recursions $\{Y_i\}_{i=0}^{n_{\delta}}$ for the SDDE, where $Y_i = X(i\delta)$. Then, our observation is taken by $\{Z_i\}_{i=0}^n$, where $Z_i = Y_{i*\Delta/\delta}$.

We have four tables in the sequel in which 500 replications of simulations are performed. Table 1 reports the test sizes for different numbers of sample size n . From Table 1, we can see clearly that the test size converges to the nominal size when the sample size n becomes large (proportional to the observation window Δ).

In Table 2, we list the test powers if the alternative hypothesis takes $H_1 : b(\eta) = a_0 - b_0\eta(0) + \theta^*b_1(\eta(-0.1))$ with $a_0 \neq 0$ (i.e. $\theta_1 = \theta^*$). Such alternatives corresponds to the cases when the perturbation of H_1 from H_0 is a constant in the drift coefficient. When a_0 departures from 0, the test power tends to one quickly. This means that indeed, the proposed test is powerful.

In Table 3, we consider the hypothesis set as $H_0 : b(\eta; \theta) = a_0 - b_0\eta(0) + \theta_0b_1(\eta(-0.1))$ versus $H_1 : b(\eta; \theta) = a_0 - b_0\eta(0) + \theta_1b_1(\eta(-0.1))$, where H_1 is indexed by θ_1 . The new feature for such an example is that $\gamma_{n,\Delta} \rightarrow 0$ in probability fails. For this case, we have $\hat{\theta}_{n,\Delta}(\mathbf{f}) = 1$ and the testing statistic becomes

$$\begin{aligned} & \left(\int_{\mathcal{E}} [\eta(0)]^2 \mu(d\eta; \theta^*) \right)^{-1/2} \hat{A}_{n,\Delta}(f_0; \theta^*) \\ &= \left(\int_{\mathcal{E}} [\eta(0)]^2 \mu(d\eta; \theta^*) \right)^{-1/2} \sqrt{\frac{\Delta}{n}} \sum_{i=m_\Delta}^n \left([a_0 - b_0Z_i + \theta_0b_1(Z_{i-m_\Delta} < 1)]Z_i + 1/2 \right). \end{aligned}$$

Note that the true value of $\int_{\mathcal{E}} [\eta(0)]^2 \mu(d\eta; \theta^*)$ is 0.1392 by performing an independent Monte-Carlo simulation in prior. Table 3 summarizes the test powers for this case. From Table 3, we also can observe that when θ_1 departures from 1, the test power tends to one quickly, which implies that the proposed test works reasonably well.

In the final Table 4, we list the test powers for different θ_0 and a_0 if the stochastic diffusion admits no delay structure in H_1 . When $a_0 = 1$, we can see that the power tends to 1 very quickly when θ_0 departs from the true value 0. This concludes our test is very powerful in distinguishing the delay structure from conventional stochastic diffusions. While if $a_0 = 0$, our tests are not becoming more powerful when θ_0 departs from 0. The reason is that $\int_{\mathcal{E}} \mathcal{A}f_0(\eta; \theta_0) \mu(d\eta; \theta_1) = 0$ in such a case, which justifies our second conclusion in Remark 1. To make our tests powerful, a different f_0 rather than $f_0(x) = x^2/2$ should be selected.

Table 1: The test sizes for different significance levels α and number of observations n with $\Delta = 10^{-3}$ and $\theta^* = 1$.

α	0.01	0.05	0.10
$n = 10^4$	0.006	0.030	0.064
$n = 10^6$	0.012	0.054	0.110

Table 2: The test powers for different values of a_0 in $H_1 : b(\eta; \theta) = a_0 - b_0\eta(0) + \theta_1b_1(\eta(-0.1))$ with $\theta_1 = 1$, $\alpha = 0.05$, $n = 10^6$ and $\Delta = 10^{-3}$.

$\alpha = 0.05$							
a_0	0.3	0.2	0.1	0	-0.1	-0.2	-0.3
Power	1.000	0.998	0.588	0.048	0.454	0.898	0.982

Table 3: The test powers for different values of θ_1 under $H_0 : b(\eta; \theta) = -b_0\eta(0) + \theta_0 b_1(\eta(-0.1))$ versus $H_1 : b(\eta; \theta) = -b_0\eta(0) + \theta_1 b_1(\eta(-0.1))$ with $\alpha = 0.05$, $n = 10^6$ and $\Delta = 10^{-3}$.

$\alpha = 0.05$							
θ_1	0.7	0.8	0.9	1.0	1.1	1.2	1.3
Power	0.936	0.770	0.286	0.048	0.460	0.962	1.000

Table 4: The test powers for different values of θ_0 and a_0 under $H_0 : b(\eta; \theta) = a_0 - b_0\eta(0) + \theta_0 b_1(\eta(-0.1))$ versus $H_1 : b(\eta; \theta) = a_0 - b_0\eta(0)$ with $\alpha = 0.05$, $n = 10^6$ and $\Delta = 10^{-3}$.

$a_0 = 1$				
θ_0	0	0.3	0.5	1
Power	0.056	0.9960	1.000	1.000
$a_0 = 0$				
θ_0	0	0.3	0.5	1
Power	0.044	0.048	0.044	0.046

4 Conclusions

We have proposed a model specification test for SDDEs using its ergodicity. Compared to model specification problems for stochastic diffusions without delay, the observation does not admit a Markovian structure. The proposed method allows us to work with the case that the stochastic diffusions have nonlinear coefficients and admits a delay structure under the null hypothesis. Through Monte Carlo simulation, we observe that the proposed test has a good test size and is indeed powerful.

Before we finalize our conclusion, we want to discuss how to apply our method if the observed window Δ is fixed. Such a case for linear SDDEs with additive diffusions has been studied in K uchler, U. and S oensen, M. (2013). Due to the special structure assumed there, it is asserted that the conditional distribution of $X_{i+1\Delta}$ on $X_\Delta, \dots, X_{i\Delta}$ is normal which plays an essential role in their study. Otherwise, a biased estimator can be concluded in K uchler, U. and S oensen, M. (2011). Because the diffusions are assumed non-linear in our problem, such a property fails and their method is not applicable here.

In our paper, the key of selecting $\mathcal{A}f_k(\cdot)$ as moment functions lies in the fact that $\widehat{A}_{n,\Delta}(f_k; \theta^*)$ is asymptotic to 0 (independent of θ^*). While for fixed Δ , the limit of $\widehat{A}_{n,\Delta}(f_k; \theta^*)$ will depends on θ^* and therefore the moment functions $\{\mathcal{A}f_k(\cdot)\}$ would not be appropriate in this case. To propose an appropriate moment estimator for such case, we need to find $g_\Delta(\eta; \theta)$ such that $g_\Delta(\eta; \theta)$ depends on the observable part in η only and $\int_{\mathcal{E}} g_\Delta(\eta; \theta^*) \mu(d\eta; \theta^*) = 0$. The choice is not easy in general because the explicit form of the invariant measure for the segment process is not obtainable. We will leave this problem for future study. To summarize, in this paper, we let $\Delta \rightarrow 0$ which leads to the closed forms of mean and variance in the asymptotic normality. Our problem can be seen as a model specification testing problems for non-linear SDDEs with high-frequency data.

5 Mathematical Proofs

Proof of Proposition 1: Note that

$$\begin{aligned} \mathbb{E} \left| \widehat{A}_{n,\Delta}(f_k; \theta) - (n\Delta)^{-1} \int_{\tau}^{n\Delta} \mathcal{A}f_k(X_t; \theta) dt \right|^2 &\leq Ln^{-1} \mathbb{E} \sum_{i=1}^n (1 + \|X_{i\Delta}\|_{\mathcal{C}})^2 \cdot \|w_{\Delta}(X_{i\Delta})\|^2 \\ &\leq Ln^{-1} \sum_{i=1}^n \sqrt{\mathbb{E}(1 + \|X_{i\Delta}\|_{\mathcal{C}})^4 \cdot \mathbb{E}\|w_{\Delta}(X_{i\Delta})\|^4} = L\Delta \end{aligned}$$

As $\sum_{n=1}^{\infty} \Delta_n < \infty$ mentioned in the introduction, we have

$$\sum_{n=1}^{\infty} \mathbb{E} \left| \widehat{A}_{n,\Delta_n}(f_k; \theta) - (n\Delta_n)^{-1} \int_{\tau}^{n\Delta_n} \mathcal{A}f_k(X_t; \theta) dt \right|^2 \leq L \sum_{n=1}^{\infty} \Delta_n < \infty.$$

By Borel-Cantelli lemma, together with the LLN in (17), we have

$$\widehat{A}_{n,\Delta_n}(f_k; \theta) \rightarrow \int_{\mathcal{C}} \mathcal{A}f_k(\eta; \theta) \mu(d\eta; \theta^*)$$

almost surely for each $\theta \in \Theta$. To prove the uniform convergence, it suffices to show $\widehat{A}_{n,\Delta}(f_k; \theta)$ is equi-continuous on each sample path. Note that

$$\begin{aligned} \sup_{\theta \in \Theta} |\partial_{\theta} \widehat{A}_{n,\Delta_n}(f_k; \theta)| &\leq n^{-1} \sum_{i=1}^n \sup_{\theta \in \Theta} |\partial_{\theta} \tilde{b}_{\Delta_n}^{\top}(Z_{i-m\Delta_n}, \dots, Z_i; \theta) \nabla f_k(Z_i)| \\ &\leq Ln^{-1} \sum_{i=1}^n (1 + \|X_{i\Delta_n}\|_{\mathcal{C}}^2) \rightarrow \text{a constant} \end{aligned}$$

almost surely. This essentially says that $\widehat{A}_{n,\Delta_n}(f_k; \theta)$ is uniformly Lipschitz on each sample path. The proof is complete.

Proof of Theorem 1: By Proposition 1, it follows that

$$\begin{aligned} &\sum_{k=1}^m \left| \int_{\mathcal{C}} \mathcal{A}f_k(\eta; \widehat{\theta}_{n,\Delta_n}(\mathbf{f})) \mu(d\eta; \theta^*) \right| \\ &\leq \sum_{k=1}^m \sup_{\theta \in \Theta} \left| \widehat{A}_{n,\Delta_n}(f_k; \theta) - \int_{\mathcal{C}} \mathcal{A}f_k(\eta; \theta) \mu(d\eta; \theta^*) \right| + \sum_{k=1}^m \left| \widehat{A}_{n,\Delta_n}(f_k; \widehat{\theta}_{n,\Delta_n}(\mathbf{f})) \right| \\ &\leq \sum_{k=1}^m \sup_{\theta \in \Theta} \left| \widehat{A}_{n,\Delta_n}(f_k; \theta) - \int_{\mathcal{C}} \mathcal{A}f_k(\eta; \theta) \mu(d\eta; \theta^*) \right| + \inf_{\theta \in \Theta} \sum_{k=1}^m \left| \widehat{A}_{n,\Delta_n}(f_k; \theta) \right| \\ &\leq 2 \sum_{k=1}^m \sup_{\theta \in \Theta} \left| \widehat{A}_{n,\Delta_n}(f_k; \theta) - \int_{\mathcal{C}} \mathcal{A}f_k(\eta; \theta) \mu(d\eta; \theta^*) \right| + \inf_{\theta \in \Theta} \sum_{k=1}^m \left| \int_{\mathcal{C}} \mathcal{A}f_k(\eta; \theta) \mu(d\eta; \theta^*) \right| \rightarrow 0. \end{aligned}$$

By the uniqueness of θ^* as the solution to $\int_{\mathcal{C}} \mathcal{A}f_k(\eta; \widehat{\theta}_{n,\Delta_n}(\mathbf{f})) \mu(d\eta; \theta^*) = 0$, we have $\widehat{\theta}_{n,\Delta_n}(\mathbf{f}) \rightarrow \theta^*$ almost surely.

Proof of Lemma 1: Without loss of generality, we assume that

$$\left(\int_{\mathcal{C}} \partial_{\theta} \mathcal{A}f_1(\eta; \theta^*) \mu(d\eta; \theta^*), \dots, \int_{\mathcal{C}} \partial_{\theta} \mathcal{A}f_m(\eta; \theta^*) \mu(d\eta; \theta^*) \right) = I,$$

otherwise we perform a local linear transformation. In the small neighborhood of θ^* , we have the following Taylor's expansion

$$\left(\int_{\mathcal{E}} \mathcal{A}f_1(\eta; \theta) \mu(d\eta; \theta^*), \dots, \int_{\mathcal{E}} \mathcal{A}f_m(\eta; \theta) \mu(d\eta; \theta^*) \right) = \theta - \theta^* + o(|\theta - \theta^*|).$$

One can steadily checked that the condition for the well-known Poincaré-Miranda theorem is met. As the convergence of $\widehat{A}_{n,\Delta}(f_k; \cdot)$ to $\int_{\mathcal{E}} \mathcal{A}f_k(\eta; \theta) \mu(d\eta; \theta^*)$ is uniform, the Poincaré-Miranda theorem is applicable for $\widehat{A}_{n,\Delta}(f_k; \cdot)$, which yields that $\widehat{A}_{n,\Delta}(f_k; \cdot) = 0$ admits a solution in Θ . The proof is complete.

Proof of Theorem 2: By the definition of $\widehat{\theta}_{n,\Delta}(\mathbf{f})$ in (2), we notice that $\widehat{A}_{n,\Delta}(f_k; \widehat{\theta}_{n,\Delta}(\mathbf{f})) = \gamma_{n,\Delta}$. Recalling the definition (18) (with $m(\mathcal{A}f_k) = 0$) and

$$\sqrt{n\Delta} A_{n\Delta}(f_k; \theta^*) = \frac{1}{\sqrt{n\Delta}} \int_{\tau}^{n\Delta} \mathcal{A}f_k(X_t; \theta^*) dt.$$

Note that $|\partial_{\theta}^2 \mathcal{A}f_k(\eta; \theta)| \leq L(\|\eta\|_{\mathcal{E}}^2 + 1)$ by Assumption 1. Using Taylor's expansion of θ , we have

$$\begin{aligned} \sqrt{n\Delta} A_{n\Delta}(f_k; \theta^*) &= \sqrt{n\Delta} [A_{n\Delta}(f_k; \theta^*) - A_{n\Delta}(f_k; \widehat{\theta}_{n,\Delta}(\mathbf{f}))] \\ &\quad + \sqrt{n\Delta} [A_{n\Delta}(f_k; \widehat{\theta}_{n,\Delta}(\mathbf{f})) - \widehat{A}_{n,\Delta}(f_k; \widehat{\theta}_{n,\Delta}(\mathbf{f}))] + \sqrt{n\Delta} \gamma_{n,\Delta} \\ &= -\sqrt{n\Delta} (\widehat{\theta}_{n,\Delta}(\mathbf{f}) - \theta^*)^{\top} \left[\frac{1}{n\Delta} \int_{\tau}^{n\Delta} \partial_{\theta} \mathcal{A}f_k(X_s; \theta^*) ds \right] \\ &\quad + O(1) \left(\sqrt{n\Delta} |\widehat{\theta}_{n,\Delta}(\mathbf{f}) - \theta^*|^2 \left[\frac{1}{n\Delta} \int_{\tau}^{n\Delta} (1 + \|X_s\|_{\mathcal{E}}^2) ds \right] \right) \\ &\quad + O(1) \sqrt{\frac{\Delta}{n}} \sum_{i=m_{\Delta}}^n \left[w_{\Delta_n}(X_{i\Delta})(1 + \|X_{i\Delta}\|_{\mathcal{E}}) \right] + \gamma_{n,\Delta_n}. \end{aligned} \quad (10)$$

By (16), we have

$$\sqrt{\frac{\Delta_n}{n}} \sum_{i=m_{\Delta_n}}^n \mathbb{E}[w_{\Delta_n}(X_{i\Delta})(1 + \|X_{i\Delta_n}\|_{\mathcal{E}})] \leq \sqrt{\frac{\Delta_n}{n}} \sum_{i=m_{\Delta}}^n \sqrt{\mathbb{E}w_{\Delta}^2(X_{i\Delta_n})(1 + \mathbb{E}\|X_{i\Delta_n}\|_{\mathcal{E}}^2)} = O(\sqrt{n\Delta_n}).$$

Again, by (5), we have

$$(n\Delta_n)^{\frac{1}{2}} |\widehat{\theta}_{n,\Delta_n}(\mathbf{f}) - \theta^*|^2 = o_p(1) (n\Delta_n)^{\frac{1}{2}} (\widehat{\theta}_{n,\Delta_n}(\mathbf{f}) - \theta^*).$$

The LLN in (17) yields that

$$\frac{1}{n\Delta_n} \int_{\tau}^{n\Delta_n} (1 + \|X_s\|_{\mathcal{E}}^2) ds \rightarrow \text{constant} \text{ and } \frac{1}{n\Delta_n} \int_{\tau}^{n\Delta_n} \partial_{\theta} \mathcal{A}f_k(X_s; \theta^*) ds \rightarrow r_k, \text{ a.s.}$$

By (10), the asymptotic normality for $A_{n\Delta}(f_k; \theta_0)$ defined in (18) yields that for any $\{\alpha_k : k = 1, \dots, m\}$

$$\sqrt{n\Delta_n} \sum_{k=1}^m \alpha_k \langle r_k(\theta^*), \widehat{\theta}_{n,\Delta_n}(\mathbf{f}) - \theta^* \rangle \rightarrow N \left(0, v^2 \left(\sum_{k=1}^m \alpha_k \mathcal{A}_0 f_k \right) \right)$$

in distribution. Since $R(\theta^*) = (r_1(\theta^*), \dots, r_m(\theta^*))$ has a rank of m , there exists a unique $\Sigma(\mathbf{f}; \theta^*)$ which is $m \times m$ -dimensional non-negative definite, symmetric matrix such that $r_k^{\top} \Sigma(\mathbf{f}; \theta^*) r_k =$

$v^2(\mathcal{A}_0 f_k; \theta^*)$ for all $1 \leq k \leq m$ given in (7). Then, (6) holds for such $\Sigma(\mathbf{f}; \theta^*)$. The proof is established.

Proof of Proposition 2: By Lemma 2 and the consistency of $\widehat{\theta}_{n,\Delta_n}(\mathbf{f})$, we know that $\Sigma^{-1/2}(\mathbf{f}; \widehat{\theta}_{n,\Delta_n}(\mathbf{f})) \rightarrow \Sigma^{-1/2}(\mathbf{f}; \theta^*)$ in probability. Therefore, Proposition 2 is a direct consequence of Theorem 2.

Proof of Theorem 3: Note that

$$\begin{aligned} \widehat{A}_{n,\Delta}(f_0; \widehat{\theta}_{n,\Delta}(\mathbf{f})) &= \left(\widehat{A}_{n,\Delta}(f_0; \widehat{\theta}_{n,\Delta}(\mathbf{f})) - \widehat{A}_{n,\Delta}(f_0; \theta^*) \right) \\ &\quad + \left(\widehat{A}_{n,\Delta}(f_0; \theta^*) - A_{n\Delta}(f_0; \theta^*) \right) + A_{n\Delta}(f_0; \theta^*). \end{aligned} \quad (11)$$

The Itô formula yields that

$$A_{n\Delta}(f_0; \theta^*) = \frac{1}{\sqrt{n\Delta}} \left(f_0(X(t)) - f_0(X(\tau)) - \int_{\tau}^{n\Delta} \sigma^\top(X_t) \nabla f_0(X(t)) dW_t \right) \quad (12)$$

in distribution. Also, note that

$$\begin{aligned} &\mathbb{E} \left| \widehat{A}_{n,\Delta}(f_0; \theta^*) - A_{n\Delta}(f_0; \theta^*) \right| \\ &= \sqrt{\frac{\Delta}{n}} \mathbb{E} \left| \sum_{i=m_\Delta}^n \left[\tilde{b}_\Delta^\top(Z_{i-m_\Delta}, \dots, Z_i; \widehat{\theta}_{n,\Delta}(\mathbf{f})) \nabla f_0(Z_i) \right. \right. \\ &\quad \left. \left. + \frac{1}{2} \text{trace} \left([\tilde{\sigma}_\Delta^\top \sigma_\Delta](Z_{i-m_\Delta}, \dots, Z_i) D^2 f_0(Z_i) \right) \right] \right. \\ &\quad \left. - \sum_{i=m_\Delta}^n \left[b^\top(X_{i\Delta}; \theta^*) \nabla f_0(X(i\Delta)) + \frac{1}{2} \text{trace} \left([\sigma^\top \sigma](X_{i\Delta}) D^2 f_0(X(i\Delta)) \right) \right] \right| \\ &\quad + \frac{1}{\sqrt{n\Delta}} \mathbb{E} \left(\sum_{i=m_\Delta}^n \left| \int_{i\Delta}^{(i+1)\Delta} b^\top(X_t; \theta^*) \nabla f_0(X(t)) - b^\top(X_{i\Delta}; \theta^*) \nabla f_0(X(i\Delta)) dt \right| \right) \\ &\quad + \frac{1}{2\sqrt{n\Delta}} \mathbb{E} \left(\sum_{i=m_\Delta}^n \left| \text{trace} \left(\int_{i\Delta}^{(i+1)\Delta} [\sigma^\top \sigma](X_t) D^2 f_0(X(t)) - [\sigma^\top \sigma](X_{i\Delta}) D^2 f_0(X(i\Delta)) dt \right) \right| \right) \\ &\leq L \sqrt{\frac{\Delta}{n}} \mathbb{E} \left(\sum_{i=m_\Delta}^n w_\Delta(X_{i\Delta}) \cdot (\|X_{i\Delta}\|_{\mathcal{C}} + 1) \right) \\ &\leq L \sqrt{\frac{\Delta}{n}} \sum_{i=m_\Delta}^n \sqrt{\mathbb{E} w_\Delta^2(X_{i\Delta}) \cdot (1 + \mathbb{E} \|X_{i\Delta}\|_{\mathcal{C}}^2)} \leq L \sqrt{n\Delta}. \end{aligned} \quad (13)$$

Using Taylor's expansion, we have

$$\begin{aligned} &\widehat{A}_{n,\Delta}(f_0; \widehat{\theta}_{n,\Delta}(\mathbf{f})) - \widehat{A}_{n,\Delta}(f_0; \theta^*) \\ &= \sqrt{\frac{\Delta}{n}} \sum_{i=m_\Delta}^n \left([\tilde{b}_\Delta(Z_{i-m_\Delta}, \dots, Z_i; \widehat{\theta}_{n,\Delta}(\mathbf{f})) - \tilde{b}_\Delta(Z_{i-m_\Delta}, \dots, Z_i; \theta^*)]^\top \nabla f_0(Z_i) \right) \\ &= \sqrt{n\Delta} \cdot M_{n,\Delta}^\top (\widehat{\theta}_{n,\Delta}(\mathbf{f}) - \theta^*) + O(1) \sqrt{n\Delta} |\widehat{\theta}_{n,\Delta}(\mathbf{f}) - \theta^*|^2 \cdot \left[n^{-1} \sum_{i=m_\Delta}^n (1 + \|X_{i\Delta}\|_{\mathcal{C}}) \right] \end{aligned}$$

$$\begin{aligned}
&= M_{n,\Delta}^\top [R^{-1}(\theta^*)]^\top \left[\sqrt{n\Delta} R^\top(\theta^*) (\hat{\theta}_{n,\Delta}(\mathbf{f}) - \theta^*) \right] + O(1) \sqrt{n\Delta} |\hat{\theta}_{n,\Delta}(\mathbf{f}) - \theta^*|^2 \cdot \left[n^{-1} \sum_{i=m_\Delta}^n (1 + \|X_{i\Delta}\|_{\mathcal{E}}) \right] \\
&= M_{n,\Delta}^\top [R^{-1}(\theta^*)]^\top \left[\frac{1}{\sqrt{n\Delta}} \int_\tau^{n\Delta} \begin{pmatrix} \sigma^\top(X_t) \nabla f_1(X(t)) \\ \vdots \\ \sigma^\top(X_t) \nabla f_m(X(t)) \end{pmatrix} dW_t \right] + o_p(1) \\
&\quad + O(1) \sqrt{n\Delta} |\hat{\theta}_{n,\Delta}(\mathbf{f}) - \theta^*|^2 \cdot \left[n^{-1} \sum_{i=m_\Delta}^n (1 + \|X_{i\Delta}\|_{\mathcal{E}}) \right] \tag{14}
\end{aligned}$$

where

$$M_{n,\Delta} = \frac{1}{n} \left\{ \sum_{i=m_\Delta}^n \partial_\theta \tilde{b}_\Delta^\top(Z_{i-m_\Delta}, \dots, Z_i; \theta^*) \nabla f_0(Z_i) \right\}.$$

By the LLN, $M_{n,\Delta_n} \rightarrow \int_{\mathcal{E}} \partial_\theta \mathcal{A}f_0(\eta; \theta^*) \mu(d\eta; \theta^*)$ almost surely as $n \rightarrow \infty$. Together with Lemma 2, (11)–(14) imply that

$$\begin{aligned}
\hat{A}_{n,\Delta_n}(f_0; \hat{\theta}_{n,\Delta_n}(\mathbf{f})) &= \langle R^{-1}(\theta^*) r_0(\theta^*), \frac{1}{\sqrt{n\Delta_n}} \int_\tau^{n\Delta} \begin{pmatrix} \sigma^\top(X_t) \nabla f_1(X(t)) \\ \vdots \\ \sigma^\top(X_t) \nabla f_m(X(t)) \end{pmatrix} dW_t \rangle \\
&\quad - \frac{1}{\sqrt{n\Delta_n}} \int_\tau^{n\Delta_n} \sigma^\top(X_t) \nabla f_0(X(t)) dW_t + o_p(1).
\end{aligned}$$

Therefore, our central limit theorem holds.

Proof of Theorem 4: In this case $\hat{\theta}_{n,\Delta} = \theta^* = \theta_0$ and the asymptotic normality in (9) follows the same way as proof of Theorem 3. Under H_1 , the testing statistic satisfies

$$\frac{1}{\sqrt{n\Delta_n}} A_{n,\Delta_n}(f_0, \theta^*) \rightarrow \int_{\mathcal{E}} \mathcal{A}f_0(\eta; \theta^*) \mu(d\eta; \theta_1),$$

almost surely by the LLN. Moreover, using the exponential ergodicity of SDDE (1) for $\theta = \theta_1$, we have

$$\lim_{n,\Delta} \mathbb{E} \left[A_{n,\Delta_n}(f_0, \theta^*) - \sqrt{n\Delta_n} \int_{\mathcal{E}} \mathcal{A}f_0(\eta(0), \eta; \theta^*) \mu(d\eta; \theta_1) \right]^2 < \infty.$$

Then, Chebyshev's inequality yields that

$$\begin{aligned}
&\mathbb{P} \left(|v^{-1}(\mathcal{A}f_0; \theta^*) \cdot A_{n,\Delta_n}(f_0, \theta^*)| \leq z_{\alpha/2} \right) \\
&\leq \mathbb{P} \left(\left| v^{-1}(\mathcal{A}f_0; \theta^*) \cdot [A_{n,\Delta_n}(f_0, \theta^*) - \sqrt{n\Delta_n} \int_{\mathcal{E}} \mathcal{A}f_0(\eta(0), \eta; \theta^*) \mu(d\eta; \theta_1)] \right| \geq L \sqrt{n\Delta_n} - z_{\alpha/2} \right) \\
&\leq L(n\Delta_n)^{-1},
\end{aligned}$$

which implies that the probability of Type II error converges to 0 with a rate of $(n\Delta_n)^{-1}$. In other words, the test power converges to one. Therefore, the proof is complete.

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Appendix: General Results on SDDEs

In this appendix, we will recall the ergodicity theory for SDDEs for our problem from Bao et al. (2020). In the sequel, we need the following assumption.

Assumption 2. (A1). σ is Lipschitz continuous; $b : \mathcal{C} \times \Theta \mapsto \mathbb{R}^d$ and $\sigma : \mathcal{C} \times \Theta \mapsto \mathbb{R}^{d \times r}$ is continuous, and bounded on bounded subsets of \mathcal{C} .

(A2). There exist two constants $\lambda_1, \lambda_2 > 0$ such that $\lambda_1 > \lambda_2 e^{-\lambda_1 \tau}$ such that

$$2\langle \xi(0) - \eta(0), b(\xi; \theta^*) - b(\eta; \theta^*) \rangle \leq -\lambda_1 |\xi(0) - \eta(0)|^2 + \lambda_2 \|\xi - \eta\|_{\mathcal{C}}^2.$$

(A3). $\sigma \sigma^\top(\cdot, \theta^*)$ is invertible with

$$\sup_{\mathcal{C}} \left(|\sigma \sigma^\top(\cdot, \theta^*)| + |(\sigma \sigma^\top)^{-1}(\cdot, \theta^*)| \right) < \infty.$$

and $|\partial_\theta b(\eta; \theta)| \leq L(1 + \|\eta\|_{\mathcal{C}})$, $|\partial_\theta \sigma(\eta; \theta)| \leq L$.

The following theorem is taken from Bao et al. (2020) concerning about the exponential ergodicity of SDDEs.

Theorem 5. Suppose Assumption 2 holds. Then the following are true.

(i) The Markov process $\{X_t\}$ admits a unique invariant measure μ on \mathcal{C} with for any $p \geq 1$

$$\sup_{t \geq 0} \mathbb{E} \|X_t\|_{\mathcal{C}}^{2p} < L_p \quad (15)$$

and

$$\sup_{t \geq 0} \delta^{-p} \mathbb{E} w_\delta^{2p}(X_t) < L_p \quad (16)$$

where L_p is a constant independent of δ .

(ii) If $|g(\eta)| \leq L \|\eta\|_{\mathcal{C}}^2$ for some $L > 0$, we have the law of large numbers

$$\frac{1}{T} \int_\tau^T g(X_t) dt \rightarrow m(g) = \int_{\mathcal{C}} g(\eta) \mu(d\eta; \theta) \quad (17)$$

almost surely.

(iii) For any $h : \mathcal{C} \mapsto \mathbb{R}$ satisfying

$$|h(\eta) - h(\xi)| \leq L \|\eta - \xi\|_{\mathcal{C}},$$

we have

$$A_T(h; \theta^*) = \frac{1}{\sqrt{T}} \int_\tau^T [h(X_t) - m(h)] dt \rightarrow N(0, v^2(h; \theta)) \quad (18)$$

in distribution, where X_t^η is the solution to (1) with initial $X_0 = \eta$,

$$R_f(\eta) = \int_\tau^\infty \mathbb{E} f(X_t^\eta) - m(f) dt$$

and

$$v^2(h; \theta) = \int_{\mathcal{E}} \mu(d\eta; \theta) \left[\mathbb{E} \left| \int_{\tau}^1 f(X_t^\eta) dt + R_f(X_1^\eta) - R_f(\eta) \right|^2 \right]. \quad (19)$$

In particular, if $h(\eta) = \mathcal{A}f(\eta(0), \eta; \theta^*)$ some twice continuously differentiable f with bounded second order derivatives, we have

$$v^2(\mathcal{A}_0 f; \theta^*) = \int_{\mathcal{E}} |\sigma^\top(\eta; \theta^*) \nabla f(\eta(0))|^2 \mu(d\eta; \theta^*). \quad (20)$$

For our testing problem, we finish the Appendix with a lemma concerning with the continuity of the invariant measure $\mu(\cdot; \theta)$ with respect to θ .

Lemma 2. *Assume Assumption 2 holds and $\sup_{\theta \in \Theta} \sup_{t \geq 0} \mathbb{E} \|X_t\|_{\mathcal{E}}^2 < \infty$. We further assume that $|\sigma(\xi, \theta) - \sigma(\eta, \theta)| \leq \lambda_3 |\xi - \eta|_{\mathcal{E}}$ with $\lambda_1 > (\lambda_2 + \lambda_3)e^{-\lambda_1 \tau}$. Then as $\theta \rightarrow \theta^*$, $\mu(\cdot; \theta) \rightarrow \mu(\cdot; \theta^*)$ in distribution with*

$$\int_{\mathcal{E}} \|\eta\|_{\mathcal{E}}^2 \mu(d\eta; \theta) \rightarrow \int_{\mathcal{E}} \|\eta\|_{\mathcal{E}}^2 \mu(d\eta; \theta^*). \quad (21)$$

Proof. Suppose $X(t)$ and $Y(t)$ be the solution of SDDE (1) with same initial and $\theta = \theta^*$ and θ_1 respectively. Note that

$$\begin{aligned} d(X(t) - Y(t)) &= [b(X_t; \theta^*) - b(Y_t; \theta_1)]dt + [\sigma(X_t; \theta^*) - \sigma(Y_t; \theta_1)]dW(t) \\ &= [b(X_t; \theta^*) - b(Y_t; \theta^*)]dt + [\sigma(X_t; \theta^*) - \sigma(Y_t; \theta^*)]dW(t) \\ &\quad + [b(Y_t; \theta^*) - b(Y_t; \theta_1)]dt + [\sigma(Y_t; \theta^*) - \sigma(Y_t; \theta_1)]dW(t) \end{aligned}$$

Therefore taking $\delta > 0$ such that $\lambda_1 > (\lambda_2 + \lambda_3 + \delta)e^{-\lambda_1 \tau}$, we have

$$\begin{aligned} d|X(t) - Y(t)|^2 &\leq \left[2\langle X(t) - Y(t), b(X_t; \theta^*) - b(Y_t; \theta^*) \rangle + |\sigma(X_t; \theta^*) - \sigma(Y_t; \theta^*)|^2 \right. \\ &\quad \left. + L(\|Y_t\|_{\mathcal{E}} |X(t) - Y(t)| + |\theta_1 - \theta^*| + 1) |\theta_1 - \theta^*| \right] dt + dM \\ &\leq [-\lambda_1 |X(t) - Y(t)|^2 + (\lambda_2 + \lambda_3 + \delta) \|X_t - Y_t\|_{\mathcal{E}}^2 + L \left(\frac{1}{4\delta} \|Y_t\|_{\mathcal{E}}^2 + |\theta_1 - \theta^*| + 1 \right) |\theta_1 - \theta^*|] dt + dM, \end{aligned}$$

where M is a martingale. Similar to the proof of Lemma 3.1 in Bao et al. (2020), we have

$$\lim_{t \rightarrow \infty} \mathbb{E} \|X_t - Y_t\|_{\mathcal{E}}^2 \leq L_\delta |\theta_1 - \theta^*|.$$

As (X_t, Y_t) is an asymptotic coupling of $\mu(\cdot; \theta^*)$ and $\mu(\cdot; \theta_1)$, this proves that $\mu(\cdot; \theta_1) \rightarrow \mu(\cdot; \theta^*)$ in distribution and (21) holds. The proof is complete. \blacksquare

Finally, we would like to make a remark that the condition in above lemma is sufficient but far from necessary. How to get a better condition is beyond the scope of our paper and thus omitted here.